Connelly Barnes CS 4810: Graphics

Acknowledgment: slides by Jason Lawrence, Misha Kazhdan, Allison Klein, Tom Funkhouser, Adam Finkelstein and David Dobkin

Traditional Pinhole Camera

• The film sits behind the pinhole of the camera.



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- Rays come in from the outside, pass through the pinhole, and hit the film plane.



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Overview

Ray Casting
 oWhat do we see?
 oHow does it look?



- Rendering model
- Intersections with geometric primitives
 oSphere
 oTriangle
- Acceleration techniques

 oBounding volume hierarchies
 oSpatial partitions
 »Uniform grids
 »Octrees
 »BSP trees

 We invert the process of image generation by sending rays <u>out</u> from the pinhole, and then we find the first intersection of the ray with the scene.



 The color of each pixel on the view plane depends on the radiance emanating from visible surfaces



• For each sample ...

oConstruct ray from eye position through view plane
oFind <u>first</u> surface intersected by ray through pixel
oCompute color sample based on surface radiance



• Simple implementation:

```
Image RayCast(Camera camera, Scene scene, int width, int height)
    Image image = new Image(width, height);
    for (int i = 0; i < width; i++) {
        for (int j = 0; j < \text{height}; j++) 
            Ray ray = ConstructRayThroughPixel(camera, i, j);
            Intersection hit = FindIntersection(ray, scene);
            image[i][j] = GetColor(hit);
    return image;
                               • Where are we looking?
                               • What are we seeing?

    What does it look like?
```

Constructing a Ray Through a Pixel Up direction View Plane back , towards P_0 right







- 2D Example: Side view of camera at P₀
 oWhat is the position of the *i*-th pixel P[i]?
 - θ = frustum half-angle (given), or field of view
 - d = distance to view plane (arbitrary = you pick)



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 $P_1 = P_0 + d*towards - d*tan(\theta)*up$ $P_2 = P_0 + d*towards + d*tan(\theta)*up$



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 $P_1 = P_0 + d*towards - d*tan(\theta)*up$ $P_2 = P_0 + d*towards + d*tan(\theta)*up$

 $P[i] = P_1 + ((i+0.5)/height)^*(P_2-P_1)$ = P_1 + ((i+0.5)/height)^*2^*d^*tan(0)^*up



2D Example:

oThe ray passing through the *i*-th pixel is defined by:

 $Ray=P_0+tV$

un

towards

d

PIT

 P_2

 $2*d*tan(\theta)$

• Where: $\mathbf{o} \mathbf{P}_0$ is the camera position oV is the direction to the *i*-th 0 pixel: $V = (P[i] - P_0) / ||P[i] - P_0||$ **o**P[i] is the *i*-th pixel location: $P[i] = P_1 + ((i+0.5)/height)^*(P_2 - P_1)$ oP_1 and P_2 are the endpoints of the view plane: $P_1 = P_0 + d$ *towards – d*tan(θ)*up

 $P_2 = P_0 + d$ *towards + d*tan(θ)*up

2D implementation:

```
Image RayCast(Camera camera, Scene scene, int width, int height)
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        image[i][height] = GetColor(hit);
    }
    return image;
}</pre>
```

Figuring out how to do this in 3D is assignment 2



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```

Ray-Scene Intersection

- Intersections with geometric primitives
 oSphere
 oTriangle
- Acceleration techniques

 oBounding volume hierarchies
 oSpatial partitions
 »Uniform (Voxel) grids
 »Octrees
 »BSP trees

```
Ray: P = P_0 + tV
Sphere: IP - OI^2 - r^2 = 0
```



Ray: $P = P_0 + tV$ Sphere: $IP - OI^2 - r^2 = 0$

Substituting for P, we get: $|P_0 + tV - O|^2 - r^2 = 0$ Algebraic Method



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Substituting for P, we get: $|P_0 + tV - O|^2 - r^2 = 0$

Solve quadratic equation: $at^2 + bt + c = 0$

where:

a = 1
b = 2 V • (P₀ - O)
c =
$$|P_0 - O|^2 - r^2 = 0$$

Algebraic Method



```
Ray: P = P_0 + tV
Sphere: IP - OI^2 - r^2 = 0
```

Substituting for P, we get: $|\mathbf{P}_0 + \mathbf{t}\mathbf{V} - \mathbf{O}|^2 - \mathbf{r}^2 = 0$ Algebraic Method

()

Solve quadratic equation: $at^2 + bt + c = 0$

where:

Generally, there are two solutions to the quadratic equation, giving rise to points P and P'. You want to return the first hit.

Ray: $P = P_0 + tV$ Sphere: $IP - OI^2 - r^2 = 0$

Geometric Method





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Geometric Method



Ray: $P = P_0 + tV$ Sphere: $IP - OI^2 - r^2 = 0$ **Geometric Method** $L = O - P_0$ $t_{ca} = L \cdot V$ (assumes V is unit length) ι_{ca} $d^2 = L \cdot L - t_{ca}^2$ if $(d^2 > r^2)$ return 0 P_0

P'

Ray: $P = P_0 + tV$ Sphere: IP - OI^2 - $r^2 = 0$ **Geometric Method** $L = O - P_0$ $t_{ca} = L \cdot V$ (assumes V is unit length) **P**' ι_{ca} $d^2 = L \cdot L - t_{ca}^2$ if $(d^2 > r^2)$ return 0 L_{hc} P_0 $t_{hc} = sqrt(r^2 - d^2)$ $t = t_{ca} - t_{hc}$ and $t_{ca} + t_{hc}$

 Need normal vector at intersection for lighting calculations



 Need normal vector at intersection for lighting calculations

N = (P - O) / IIP - OII



Ray-Scene Intersection

- Intersections with geometric primitives
 OSphere
 Trionalo
 - » Triangle

Ray-Triangle Intersection

- First, intersect ray with plane
- Then, check if point is inside triangle



Ray-Plane Intersection

```
Ray: P = P_0 + tV
Plane: P \cdot N + d = 0
```

Substituting for P, we get: $(\mathbf{P_0} + t\mathbf{V}) \cdot \mathbf{N} + d = 0$

Solution: $t = -(P_0 \cdot N + d) / (V \cdot N)$





Ray-Triangle Intersection I

Check if point is inside triangle algebraically

```
For each side of triangle

V_1 = T_1 - P_0

V_2 = T_2 - P_0

N_1 = V_2 \times V_1

if ((P - P_0) • N_1 < 0)

return FALSE;
```

end



Ray-Triangle Intersection II

Check if point is inside triangle parametrically

```
Every point P inside the triangle can be
expressed as:

P = T_1 + \alpha (T_2 - T_1) + \beta (T_3 - T_1)
where:

0 \le \alpha \le 1 \text{ and } 0 \le \beta \le 1
\alpha + \beta \le 1
T_1
P
B(T_3 - T_1)
```

 T_2

Ray-Triangle Intersection II

Check if point is inside triangle parametrically

 P_0

 T_3

β(T₃-T₁)

 T_2

U/12-

Solve for α , β such that: $P = T_1 + \alpha (T_2 - T_1) + \beta (T_3 - T_1)$ Check if point inside triangle. $0 \le \alpha \le 1 \text{ and } 0 \le \beta \le 1$ $\alpha + \beta \le 1$

Other Ray-Primitive Intersections

- Cone, cylinder, ellipsoid:
 oSimilar to sphere
- Box

oIntersect 3 front-facing planes, return closest

- Convex polygon
 oSame as triangle (check point-in-polygon algebraically)
- Concave polygon
 oSame plane intersection
 oMore complex point-in-polygon test

Ray-Scene Intersection

Find intersection with front-most primitive in group

```
Intersection FindIntersection(Ray ray, Scene scene)
    min t = \infty
    min shape = NULL
                                                          Ε
    For each primitive in scene {
         t = Intersect(ray, primitive);
         if (t > 0 \text{ and } t < \min t) then
              min_shape = primitive
              min t = t
    return Intersection(min t, min shape)
}
```

Next Lecture

- Intersections with geometric primitives
 oSphere
 oTriangle
- Acceleration techniques

 oBounding volume hierarchies
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